



# GD Real Testing



# GD REAL TESTING



GD Real Testing focuses on the research and development and promotion of track maintenance equipment, providing digital and intelligent products as well as services for railway and subway operators.

## Our Mission

GD Real Testing adheres to the principle of "**understanding the world through data, empowering the world with data**" and the mission of "**Enhancing traffic safety**"

## Main Business

GD Real Testing's main products and services are **Ground penetrating radar detection system, 3D Laser scanning system, Rail flaw detection system, and related detection services**. Additionally, **customised track comprehensive inspection system solutions is also available**.

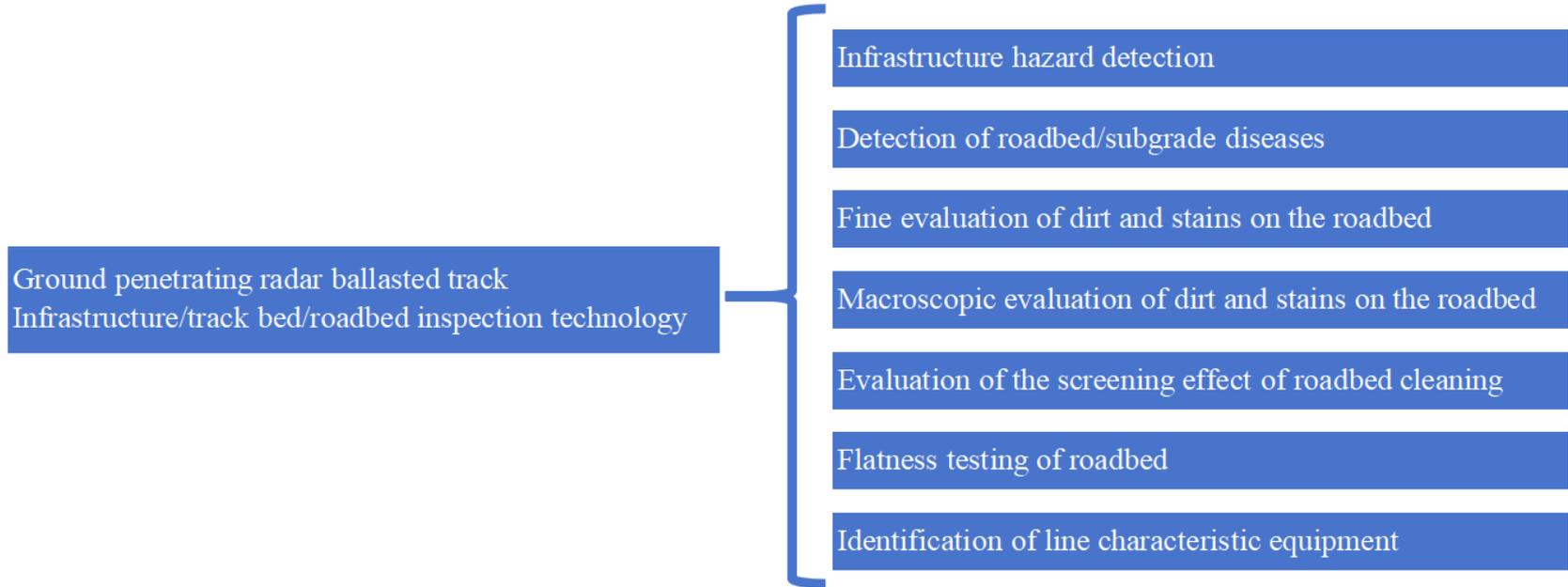
- 1 Ground Penetrating Radar Detection System
- 2 3D Laser Scanning System
- 3 Ultrasonic Rail Flaw Detection
- 4 Dual-use intelligent comprehensive inspection vehicle
- 5 Adhesive Insulation Joint
- 6 Anti-Loose Washer
- 7 Related Detection Services



Ground Penetrating Radar Detection System



## • System Introduction



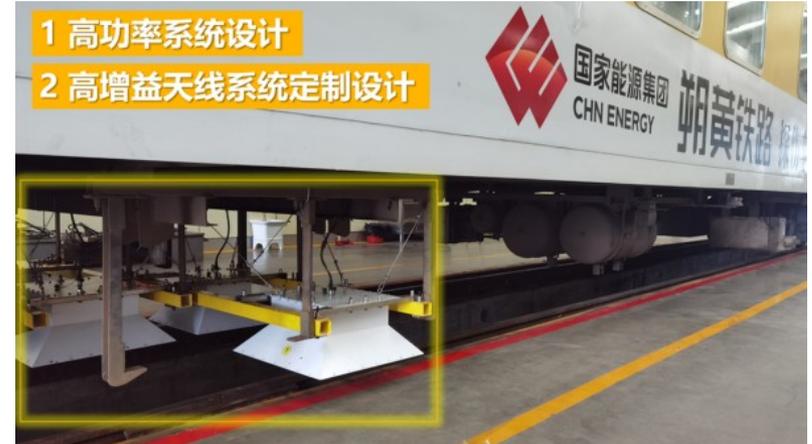
**Tunnel Infrastructure Risks:** Identify and locate deep crushing, water-rich areas, voids and fractures, subsidence and uncompaction of the infrastructure, etc;

**Subgrade defects:** subgrade voids, settlement, fragmentation, water rich areas, etc;

**Ballast bed contamination:** ballast bed contaminants distribution, areas rich in water, slurry boiling, mud overflow, evaluation of large machine cleaning effectiveness, detection of ballast deficiency, etc;

- Test Case

The comprehensive inspection of in the Shuohuang heavy-haul railway of China National Energy Group



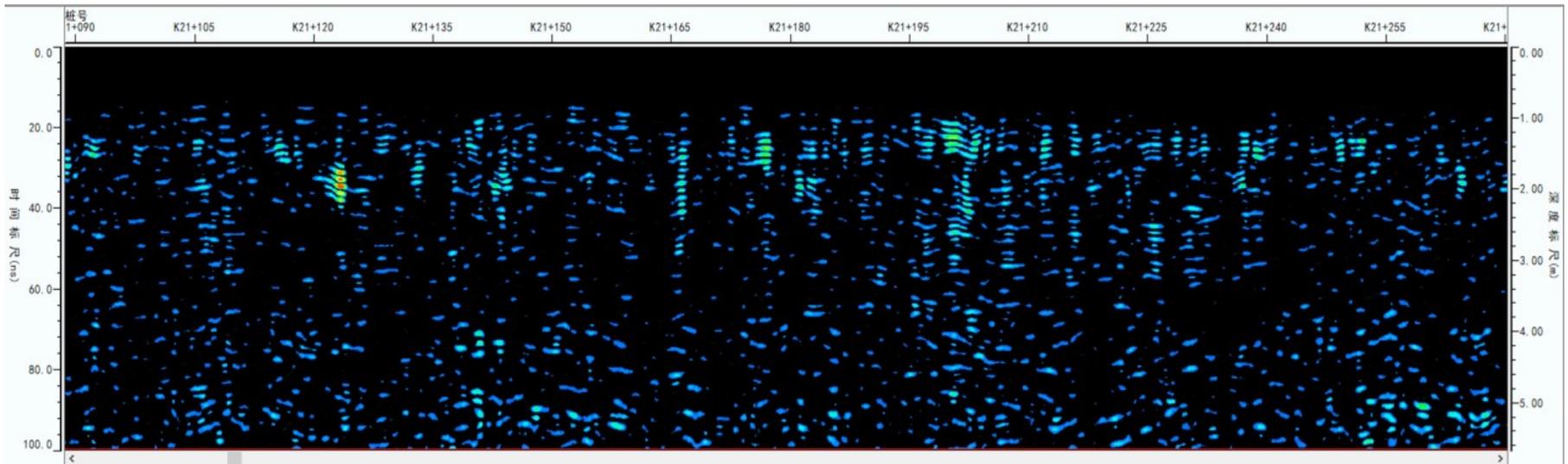
China Railway Shanghai Bureau Railway ballast bed contamination and subgrade defects detection



- Results Display

## Tunnel subgrade inspection

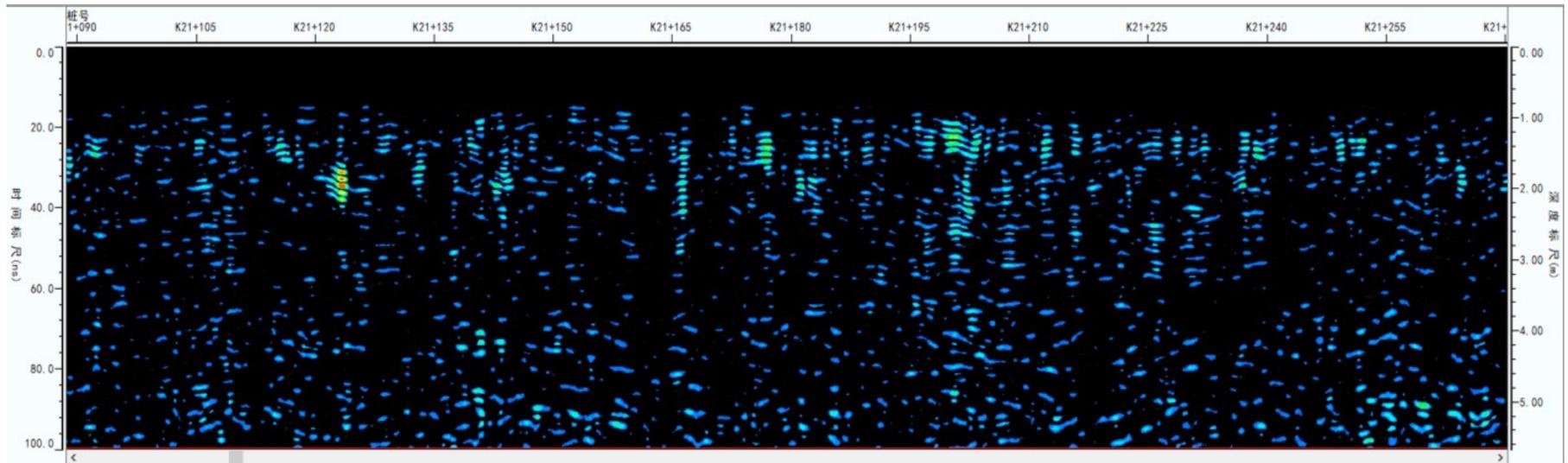
- Radar map of tunnel basement in good condition



- Results Display

## Tunnel subgrade inspection

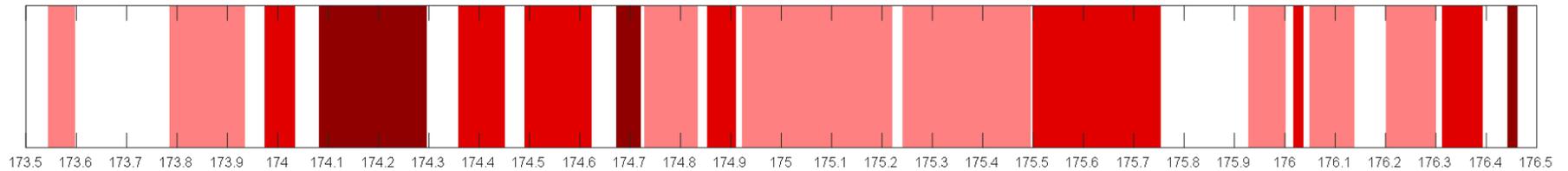
- Radar map of tunnel basement in good condition



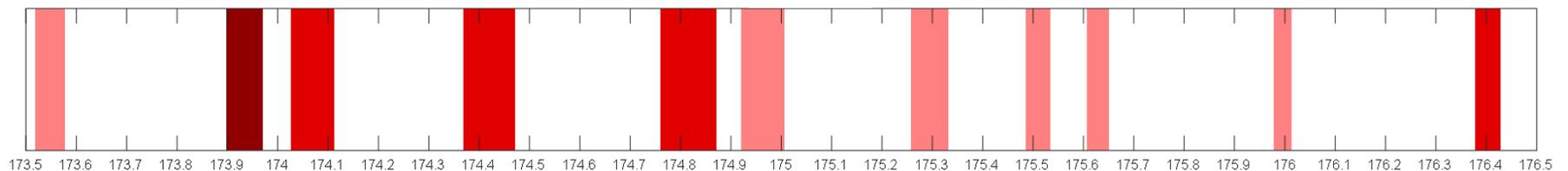
## • Results Display

### Tunnel subgrade inspection

Tunnel basement disease distribution map



Tunnel basement disease distribution map

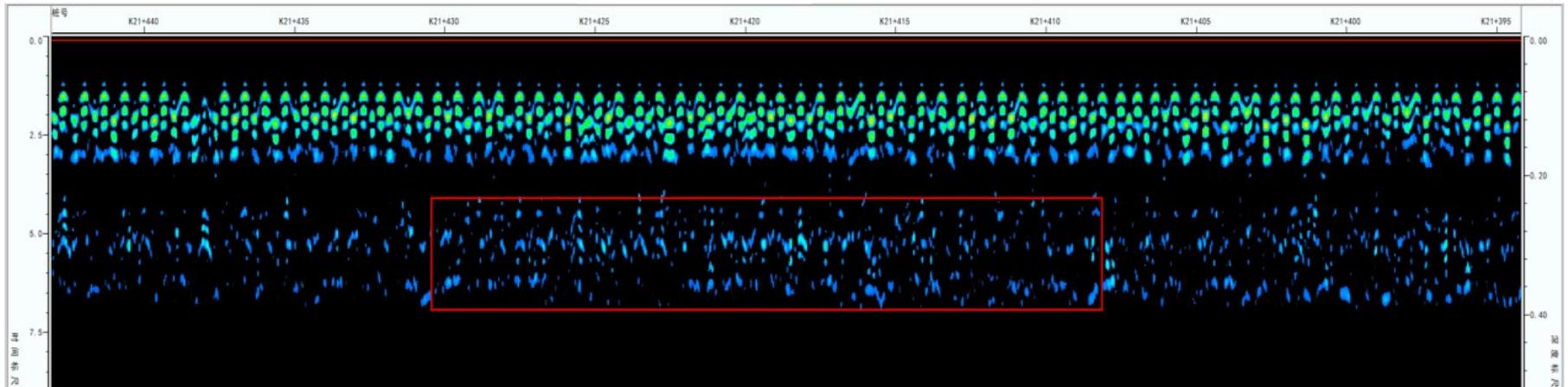


里程/公里

- Results Display

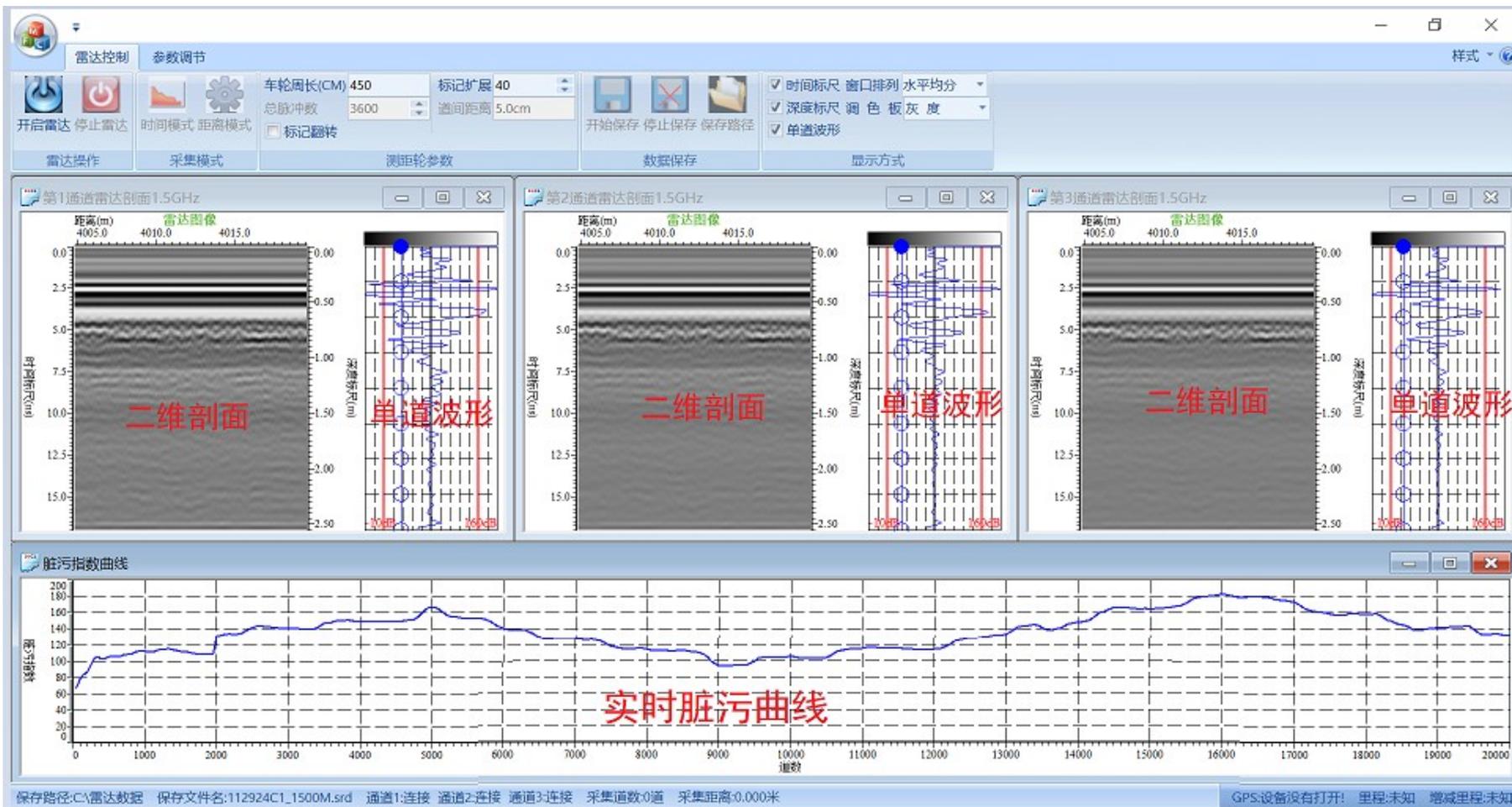
## Distribution of contamination on the subgrade

contamination distribution diagram of a line



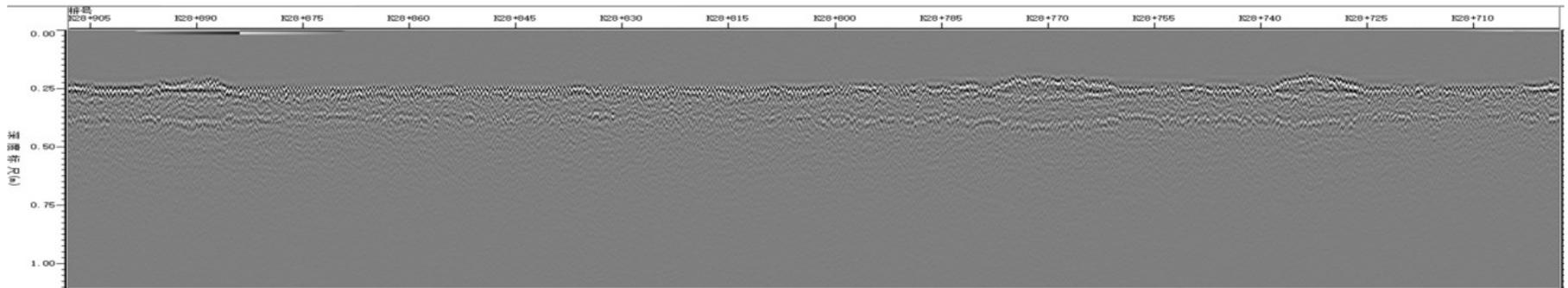
## • Results Display

### Real time contamination curve output



- Results Display

## Excavation verification(Sand content in subgrade)



- **Advantages**

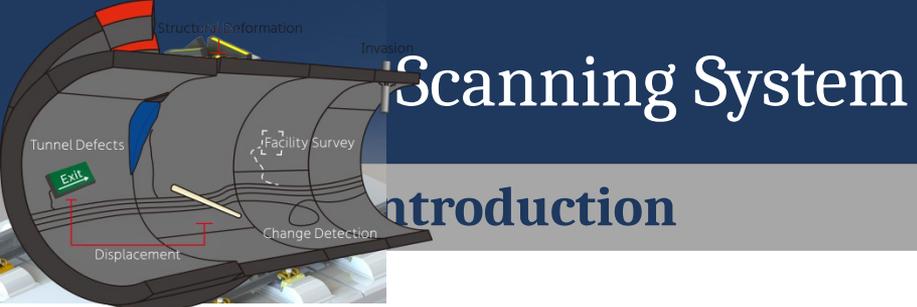
Through long-term cooperation with **Shuohuang Company** and **the Shanghai Railway Bureau**, a **substantial experimental data bank** has been established. Based on **excavation verification, size calibration**, and experiments on the **dielectric constant of contaminated track beds**, GD Real Testing Company has achieved significant results in the **quantitative detection** of track bed contamination and algorithm research on track bed contamination. These achievements can be summarized as follows:

1. **A quantitative evaluation system based on radar detection of track bed fouling rates;**
2. **An assistance decision-making and screening quality evaluation system;**
3. **Customized development of integrated ground-penetrating radar detection equipment for heavy-haul railway track bed/subgrade/foundation structures;**
4. **The first implementation of "condition-based repair" guided by detection data for screening construction, leading to significant savings in staff costs.**

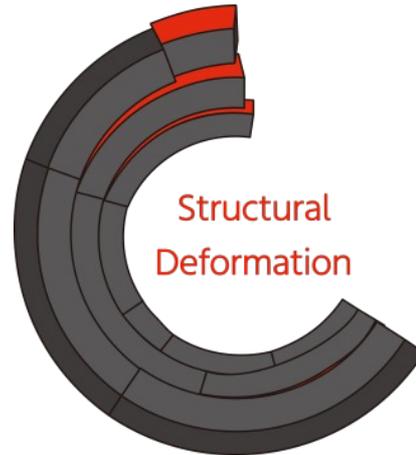


**3D Laser scanning system**

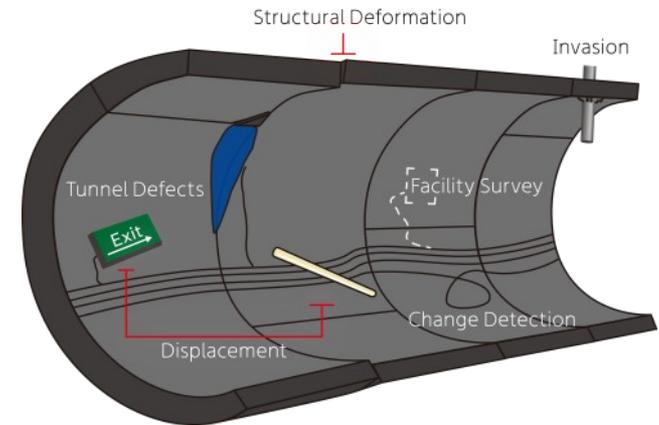




Electric railway vehicle



Structural Deformation



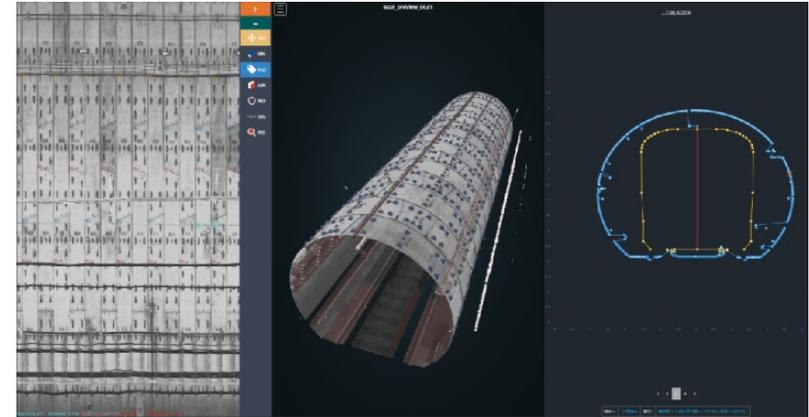
Tunnel Defect + BIM Model

The **mobile laser scan system** is designed for railway tunnel inspection and **digital twin**. Outcomes include **tunnel structural deformation, defect inspection, clearance measurement, BIM/Mesh model, facility survey**, etc. The system can be mounted on railway vehicle, enabling you to gather **lidar data and HD images** in one way efficiently.

## • Results Display

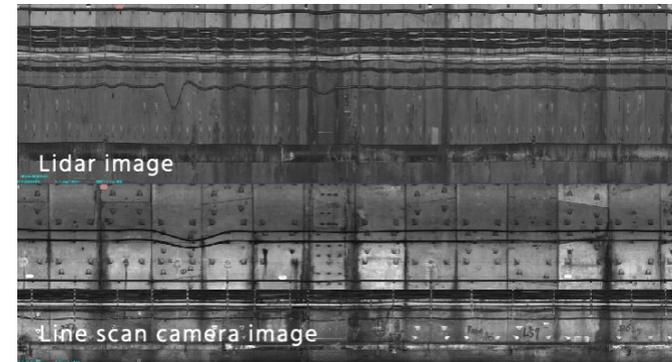
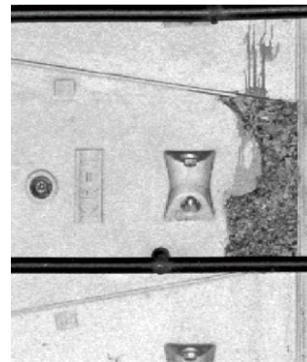
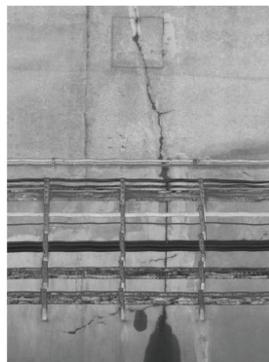
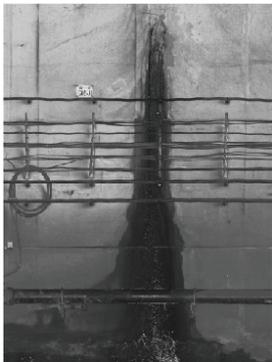
### Tunnel Structural Deformation

- Lidar intensity/depth image
- Circular convergence and segment dislocation
- Clearance
- Multi-period changes
- CAD drawing, excel sheet, thematic image, etc



### Defect Inspection

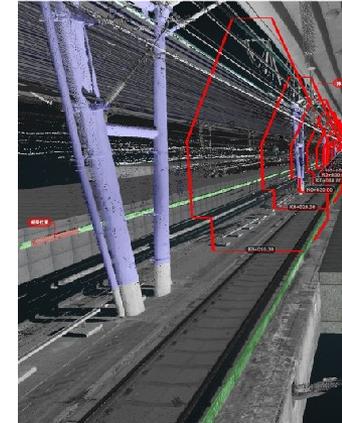
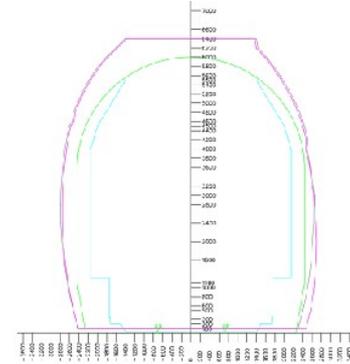
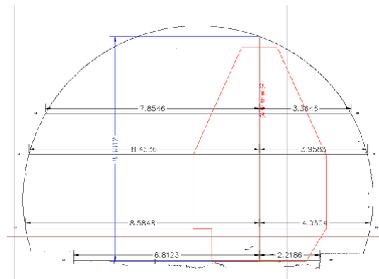
- Image resolution up to 0.2mm/pixel
- Tunnel defects, facilities and changes inspection
- Multi-view analysis: lidar image, map, HO image, GPR image, cross-section drawing



## • Results Display

### Clearance Gauge

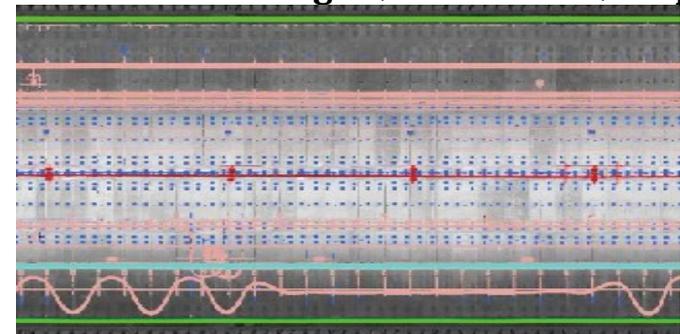
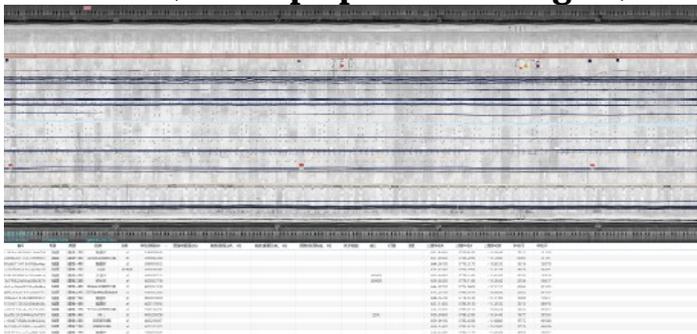
- Cross-section CAD drawing & Excel report
- User-defined vehicle, profile, gauge, .dxf template
- Clearance gauge report



### AI Image Recognition

- Utilizing data classification method and AI recognition algorithm
- Metro Shield Tunnel Feature Recognition
- Recognition rate ( $\geq 90\%$ )
- Bolt, Segment, OCS, Cable Signboard, Track bed, Fastener, Escape platform Target, Rail track, Pipe

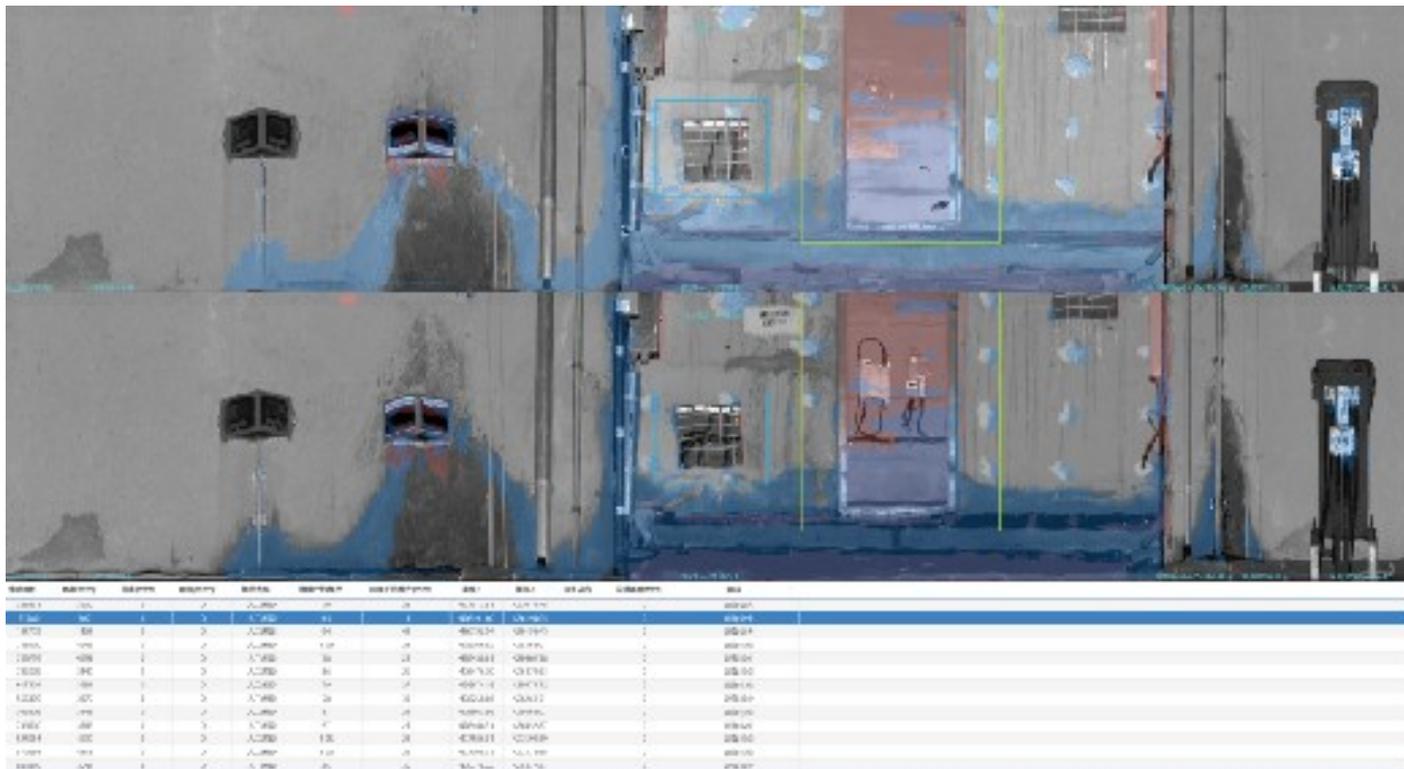
- Bolt, Segment, OCS, Cable Signboard, Track bed, Fastener, Escape platform Target, Rail track, Pipe



- Results Display

## Change Detection

- Multi-period comparison based on coordinate and laser intensity
- High light and vectorization of water leakage, cable displacement and facility changes
- 1 cm×1 cm identifiable at 1.8 km/h with Z+F 9012 scanner

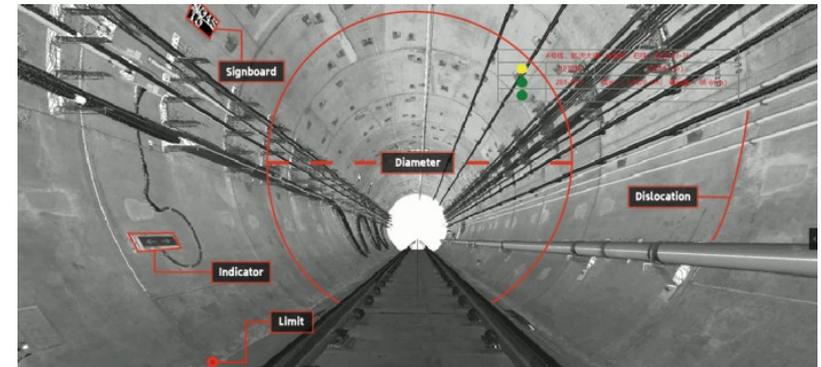


- **Results Display**

## Digital Twin

### Roaming Video

- **MultiView Rendering**  
Video(Perspective/Front/Otho,etc)
- **Data integration: deformation, clearance, defects and facilities etc**



### Feature & Model

- **Interactive and AI-aided feature extraction**
- **Revit model: tunnel, track, catenary, evacuation route, communication device box, fire pipeline, etc.**
- **OsGB model, etc.**





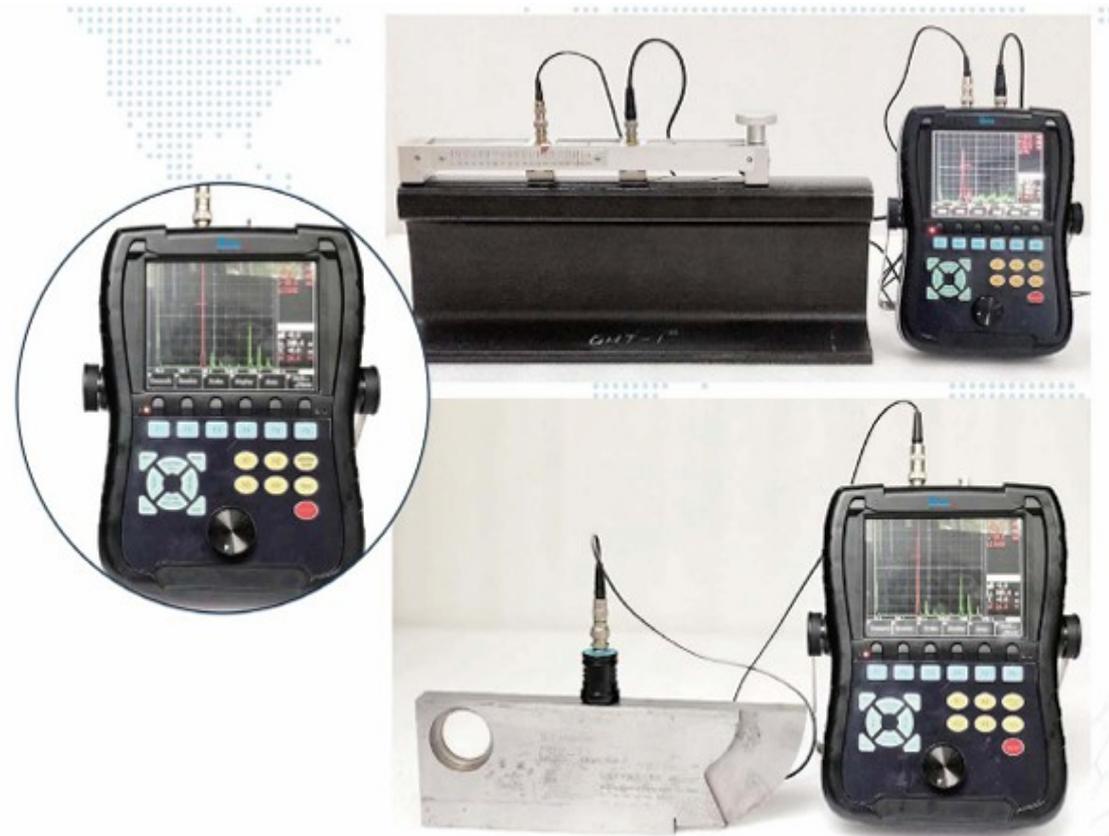
## Ultrasonic Rail Flaw Detection



# Ultrasonic Rail Flaw Detection

## • CK2108 Ultrasonic Flaw Detector

CK2108 ultrasonic flaw detector adopt industrial advanced square wave excitation technology, which has stable performance, light and portable, convenient operation and high price-to-cost rate. The display screen adopts high-resolution ratio TFT screen (640\*480), which is fully competent to work outdoors and in direct sunlight; High-performance lithium battery, the continuous working time can reach 8 ~ 11 hours and the weight is only 1.5kg, so it is suitable for non-destructive testing in railway transportation departments.



# Ultrasonic Rail Flaw Detection

- RTS18-B Dual Rail Hand push Ultrasonic Flaw Detector



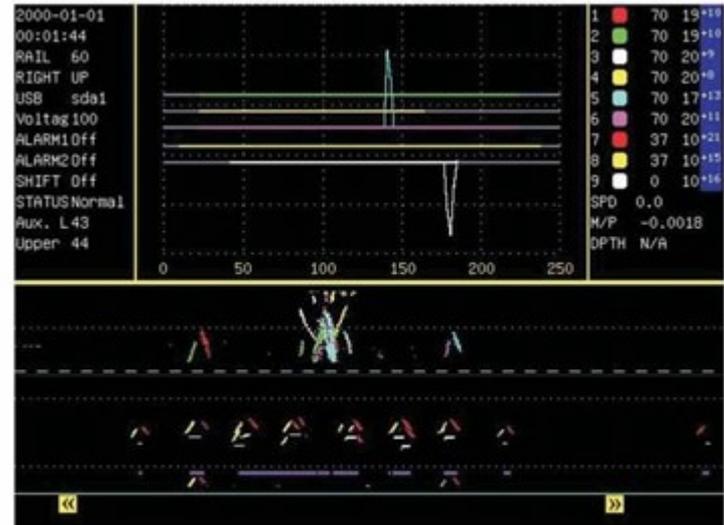
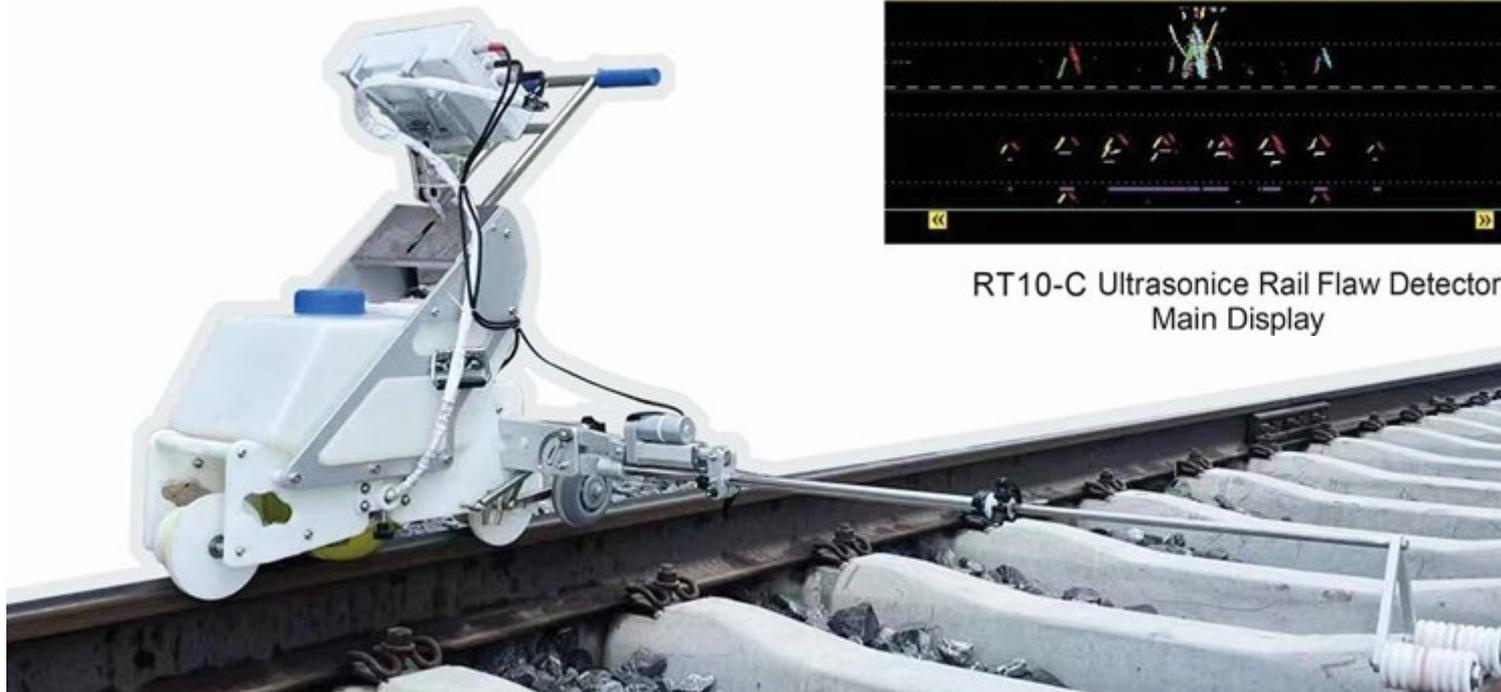
9 channel Roller Search Unit(wheel probe) High Brightness Rugged Tablet Display

**The trolley can be easily assembled and disassembled. Each part is no more than 10kg, the weight of the whole trolley is less than 45kg. The assembly time is less than 3 minutes.**

# Ultrasonic Rail Flaw Detector

- RT10-C Ultrasonic Rail Flaw Detector

RT10-C is our upgraded version of RT10-B ultrasonic rail flaw detector. The most distinguished feature is RT10-C instrument offers simultaneous A-scan and B-scan.



RT10-C Ultrasonic Rail Flaw Detector  
Main Display

# Ultrasonic Rail Flaw Detection

- UR18-D Ultrasonic Rail Flaw Detection Electrical Vehicle

UR18-D Ultrasonic Rail Flaw Detection vehicle adopts ultrasonic wheel probe technology, with two 9 channels ultrasonic wheel probes. Data from total 18channels of two rails are displayed on the military grade high-intensity rugged Laptop in the form of B-scan.

UR18-D Ultrasonic Rail Flaw Detection vehicle can effectively detect the flaws at the rail head, bolt hole breaks and transverse defect at rail base. The detection rate can be up to more than 95%. The detection vehicle equips with a smart defect recognition system for automatically pop-up a zoomed window with view of the alarm section which is convenient for the operator to make decision in real time, The vehicle frame is made of Titanium alloy with patented split design, each part is less than 60kg.

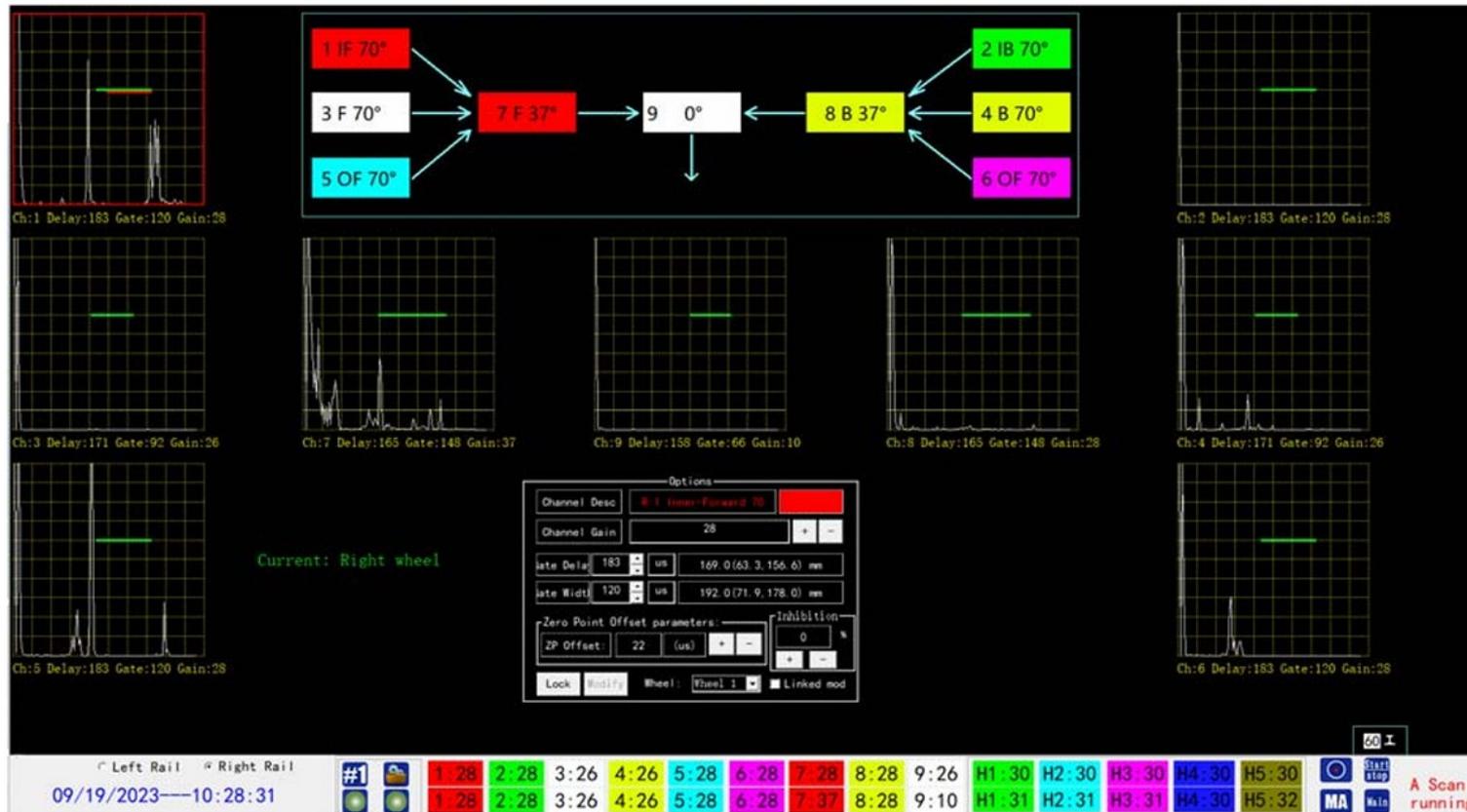
Titanium alloy maintains great strength while decreasing the weight. The vehicle uses lithium battery for environmental protection and can test with a detection speed of 15 kilo meters per hour. This ultrasonic rail flaw detection vehicle can work in very worse environment 30C~45C(-220F~113F)



- Results Display

### A-Scan

The following is a typical A-scan picture on the test screen. It shows the A-scan waveforms of all 9 channels of right rail.



- Results Display

### B-Scan

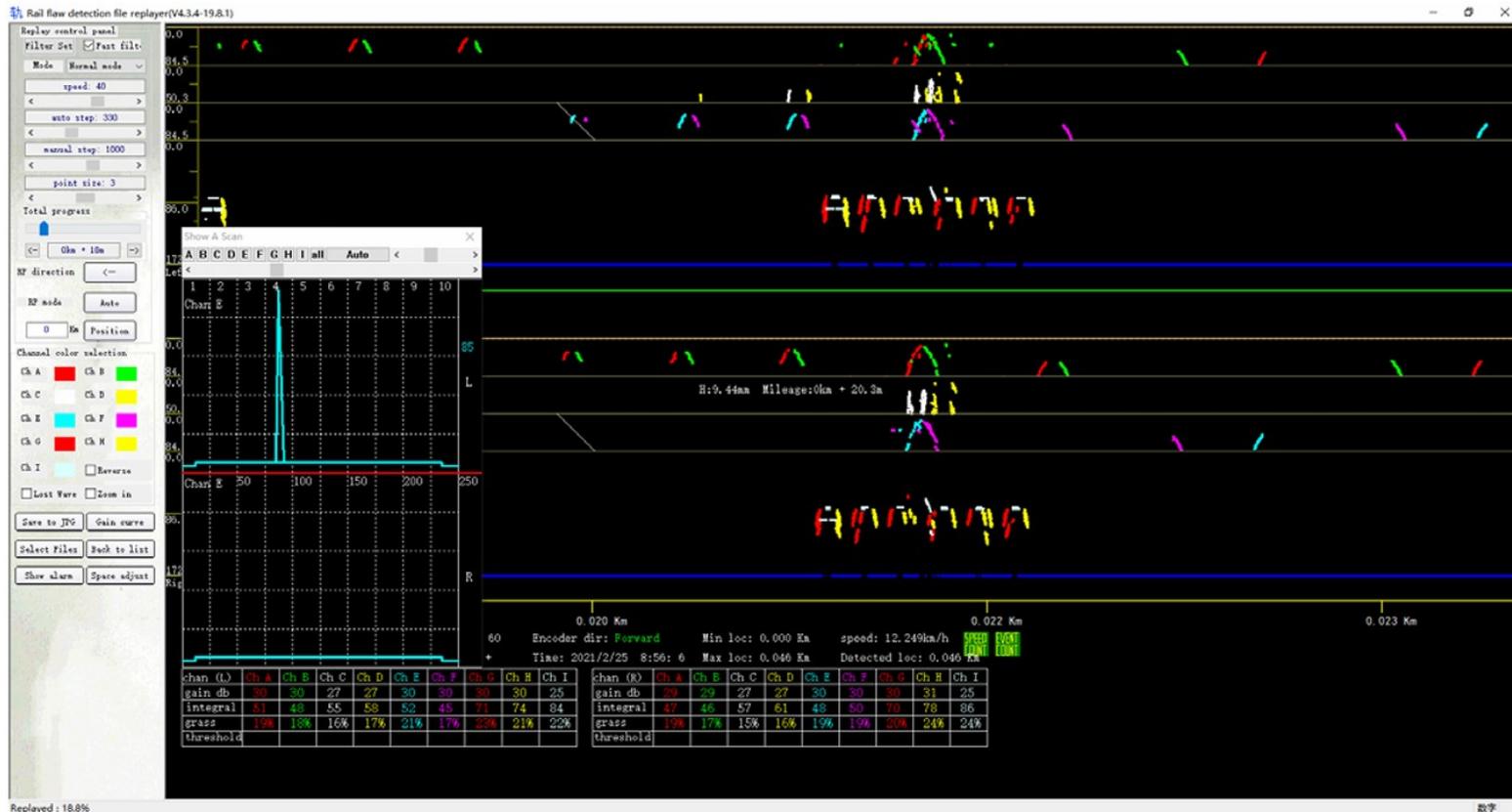
The following is a typical B-scan picture on the test screen.



- Results Display

## Replay Software

All the information recorded during the test can be replayed. The following is a typical data replay on the screen.



# Ultrasonic Rail Flaw Detection

- GT6600 Hi-Rail Ultrasonic Rail Flaw Detection Vehicle



Channels: total 26 channels, 13 channels on each rail. In each rail, there are SIX straight 70 degree channels (forward and backward), FOUR skewed 70 degree channels (gauge skewed and field skewed, forward and backward), TWO 37 degree channel, ONE 0 degree channel.

- GT6600 Hi-Rail Ultrasonic Rail Flaw Detection Vehicle

- Results Display

### Sample B-scan Image



# Ultrasonic Rail Flaw Detection

## • RTI RFDV'S

RTI's RFDV Vehicles test at high Speed.



**RTI's RFDV's are all accredited to AS/RISSB 7502:2016 Road Rail Vehicle standard.**

Additional client HiRail requirements can be accommodated.

RTI's testing methodologies include:

- Single Vehicle Stop and Confirm, defects verified within minutes
- Chase Vehicle (various modes of defect confirmation depending if the Chase Vehicle is on or off-track). Suspect are located by odometer and high accuracy differential GPS (less than 0.5m).
- Test Through/Non- Stop testing with Hunter Post Analysis

## ● 8800SX System

When the RTI 8000SX system was introduced in 1998 it was considered the highest resolution system in the industry with 1,024 samples per frame.

Today, the RTI 8800SX system collects 65,536 samples per frame. This provides sufficient head room so as not to saturate any signals and thus, achieve accurate automated defect recognition and sizing.



The 8800SX Automated Rail Flaw Detection System was released in 2016. The electronics and racking hardware accommodates the 8800SX Ultrasonics and provisions for RTI's Optional SurfaceMap System, Video Cameras and other optional technologies. The sub-rack allows for up to 80 ultrasonic channels.

The 8800SX architecture allows for Real Time channel-to-channel, frame-on-frame correlation of linear and phased array transducer capability utilising a high speed bus.

## ● Smart Track Test Carriage with Roller Search Units / Probe Wheel



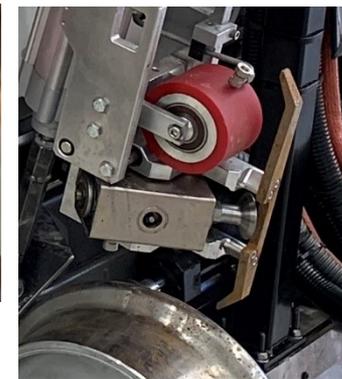
Smart Track Test Carriage on a 4WD Hi Rail



Smart Track Test Carriage within trolley for Rail bound vehicles



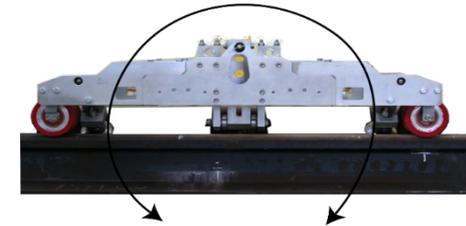
Typical test carriage holds two Roller Search Units (RSU's) with a total of 22 transducers (system can take up to 32 channels).



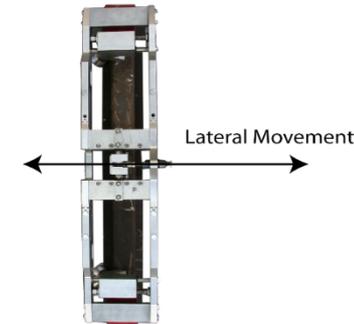
### Gauge Tracking System

Maintaining gauge is controlled by either spindle rollers or gauge rollers (depending on infrastructure requirements).

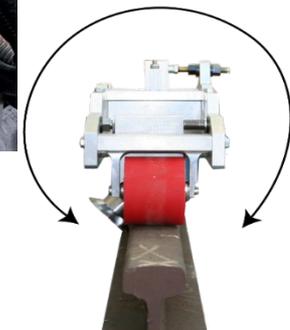
Longitudinal Movement



Lateral Movement



CANT Movement



## • Probe Wheel configuration

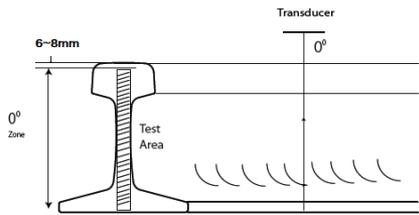


Figure 1 - Scanning Area 0° Type Probe

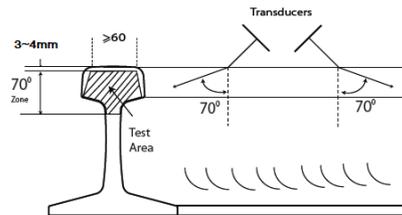


Figure 2 - Scanning Area 70° Type Probe

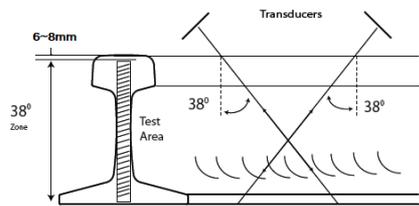


Figure 3 - Scanning Area 38° Type Probe

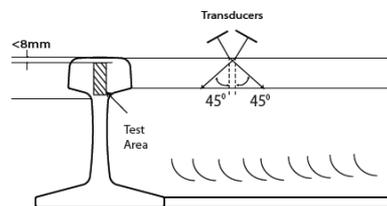


Figure 4 - Scanning Area VSH 45° Type Probe

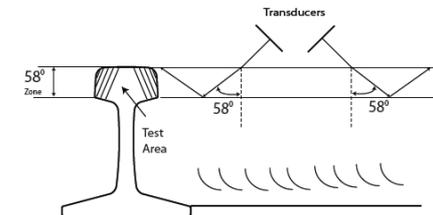
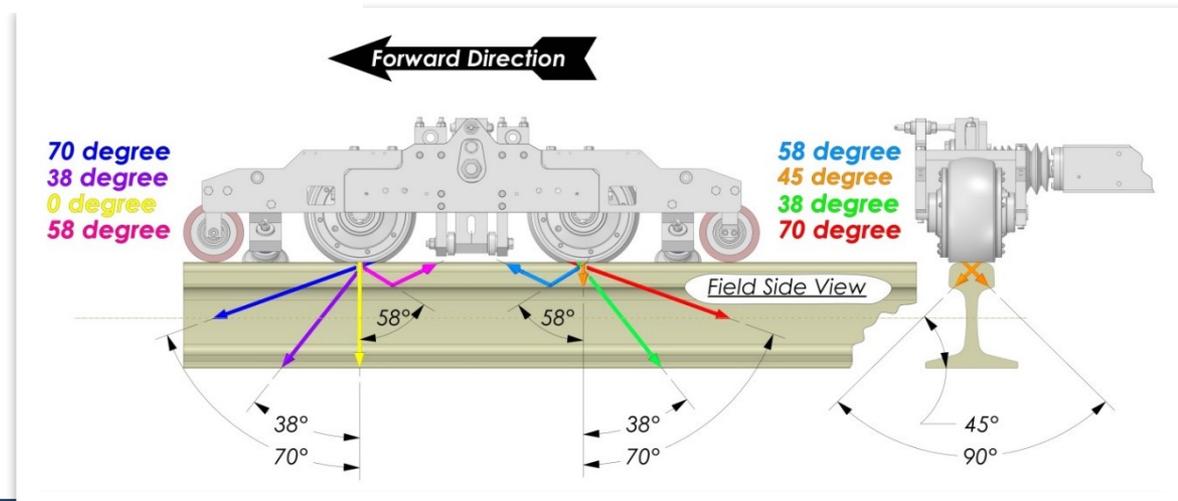


Figure 5 - Scanning Area 58° RHOM Type Probe  
(optionally equipped)

Each carriage side mounts two probe wheels containing up to 16 channels (32 in total - can be optioned with more channels if required).

Configuration:

- 0° probes cover the centre section of the rail head, web and foot to detect horizontal split head and rail height.
- 38° probes cover the centre section of the rail head, the web and the centre section of the foot to detect transverse defects, bolt-hole cracks and weld defects.
- 70° probes cover the rail head to detect transverse defects, some surface defects and weld defects. Brush type is used.
- 45° probes cover the part of the rail head to detect vertical split head.
- 58° ROM probes (optionally equipped) cover the gauge and field corners to detect defects at the corners using second reflections.



## • Automated System Calibration

### SmartCal™

First introduced in our 8000SX system. It provided a significant change in detection repeatability and for the first time RTI saw consistent data results from survey to survey across Operators.

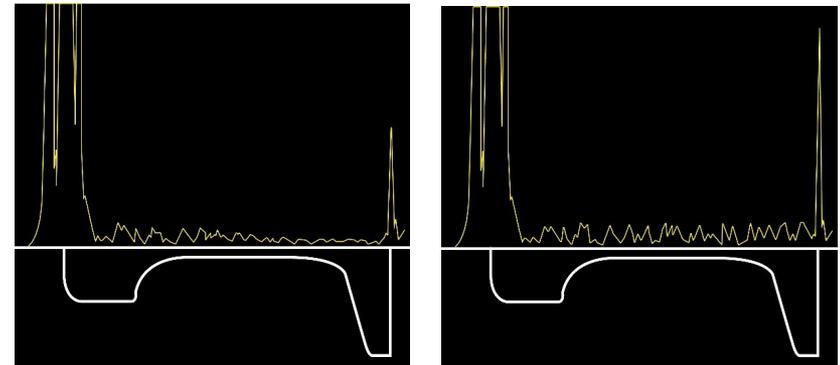
The use of SmartCal into the 8800SX makes it possible to have absolute reference for each channel and for each position of depth by monitoring grain levels at different depths.

SmartCal adjusts the Depth Gains (Time Gains) individually for every channel with up to 32 individual gain points per channel.

### The Benefits of SmartCal™

- Remove subjectivity of operator
- Uniform signal response over the entire height of the rail (compensates for signal attenuation over distance travelled and in rail)
- Compensates for signal attenuation to improve detection of TDs under RCF
- Transducer gain drift caused by temperature variations is completely eliminated
- Fully compensates for non-linearity between transducers

**The SmartCal system is exclusive to RTI and contributes significantly to both the high productivity and high precision of the 8800SX system.**



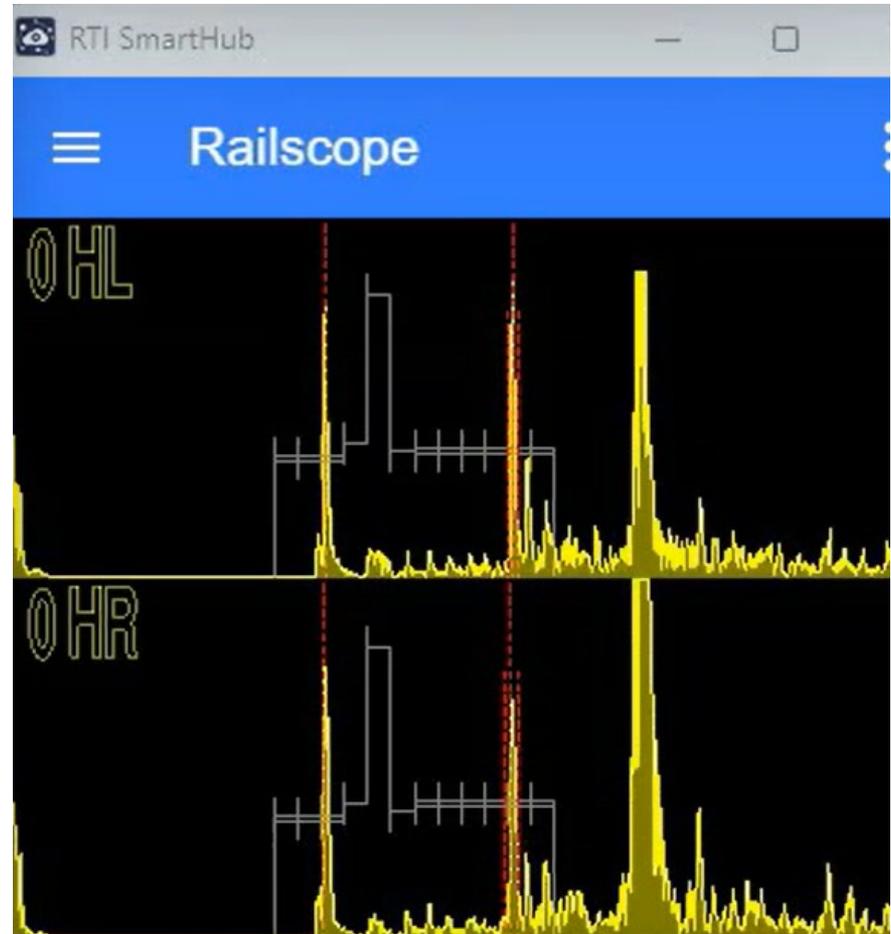
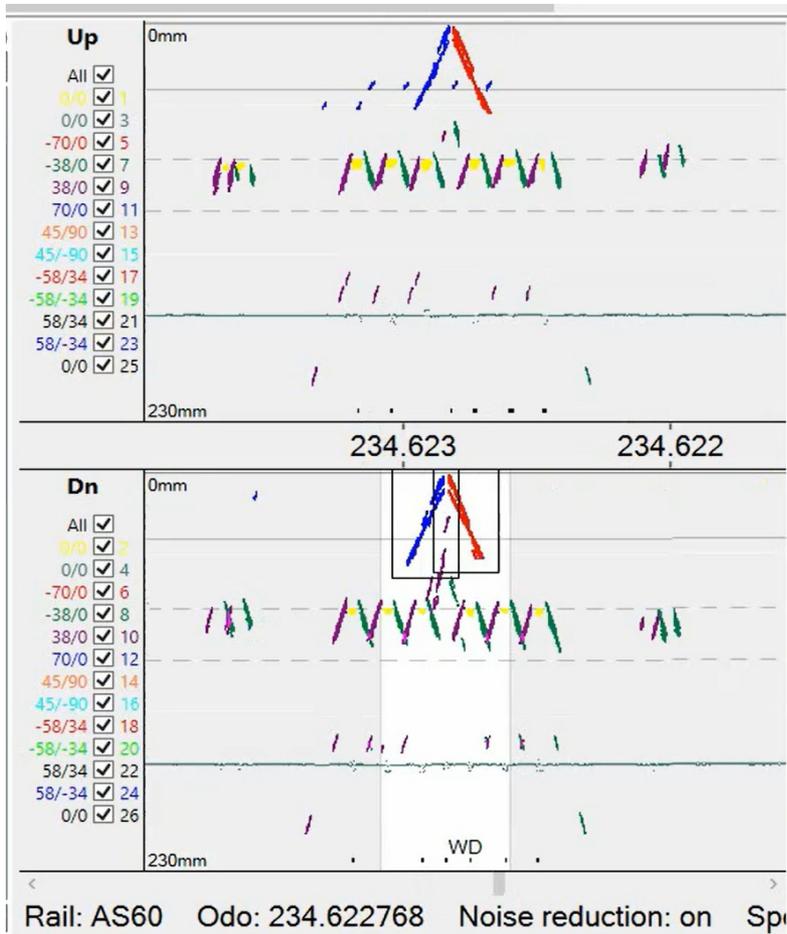
0 Degree no SmartCal  
with SmartCal

0 Degree



• Hunter Analysis System

A and B Scan and Railscope



## Hunter Analysis System

### Real Time Analysis - (Hunter)

Common View Tools Analysis Realtime mode Realtime workplace +

Classification: ARTC Profile: ARTC (16 bits) (v. 2)

Defects	Type	Odo	Channels	Rail
<input checked="" type="checkbox"/>	H WD	234.623	11, 5	Up
<input checked="" type="checkbox"/>	H WD	234.623	12, 6	Dn
<input checked="" type="checkbox"/>	H Head	234.684	6, 10	Dn
<input checked="" type="checkbox"/>	H Head	234.693	14, 6, ...	Dn
<input checked="" type="checkbox"/>	H LBWE	234.691	26	Dn
<input checked="" type="checkbox"/>	W Web	234.693	10	Dn
<input checked="" type="checkbox"/>	H Head	234.704	5, 11	Up
<input checked="" type="checkbox"/>	H Head	234.705	6, 12	Dn
<input checked="" type="checkbox"/>	H WD	234.706	11, 5	Up
<input checked="" type="checkbox"/>	H WD	234.707	12, 6	Dn
<input checked="" type="checkbox"/>	H Head	234.709	5, 11	Up
<input checked="" type="checkbox"/>	H Head	234.713	6, 8	Dn
<input checked="" type="checkbox"/>	H LBWE	234.716	26	Dn
<input checked="" type="checkbox"/>	W Web	234.731	7, 9	Up
<input checked="" type="checkbox"/>	H LBWE	234.732	26	Dn
<input checked="" type="checkbox"/>	H Head	234.732	14, 16	Dn
<input checked="" type="checkbox"/>	H LBWE	234.734	26	Dn
<input checked="" type="checkbox"/>	W Web	234.737	8	Dn
<input checked="" type="checkbox"/>	H Head	234.738	5, 7, 9...	Up
<input checked="" type="checkbox"/>	H WD	234.744	11, 5	Up
<input checked="" type="checkbox"/>	H WD	234.744	12, 6	Dn
<input checked="" type="checkbox"/>	H LBWE	234.875	25	Up
<input checked="" type="checkbox"/>	H LBWE	234.875	25	Up
<input checked="" type="checkbox"/>	W Web	234.878	7, 9	Up

**Up**

0mm

230mm

234.623      234.622

**Dn**

0mm

230mm

WD

Current odo: 234.408612

Odo diff: -214.2m

GPS diff: 214.8m

Analysis delay: 25.8m

Current speed: 23 kph

Current height: Left 168.4, Right 168.4

Recording state: Recording

Test carriage: [Icons]

Water (Ltr/km): 12.1

Water usage(L): 28.1

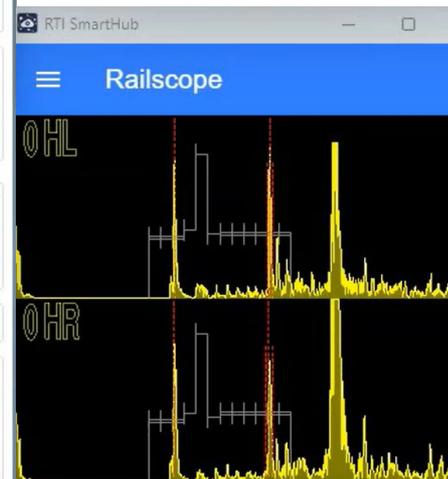
Proxy server: Connection: On

GPS: Lat: -32.6015271, Lon: 151.197662, Altitude: 39.03, Odo factor: 4.010, GPS speed: 22.59 kph

Flush buffer

Rail: AS60 Odo: 234.622768 Noise reduction: on Sp

ARTC-10001...



## • Surface Map

### Detection Capabilities

- Rolling Contact Fatigue (RCF)
- Surface Breaking Crack Detection in Switches and Frogs
- Squats
- Engine Burns
- Welds (Flashbutt, Aluminothermic & Manual Arc)
- Rail Ends

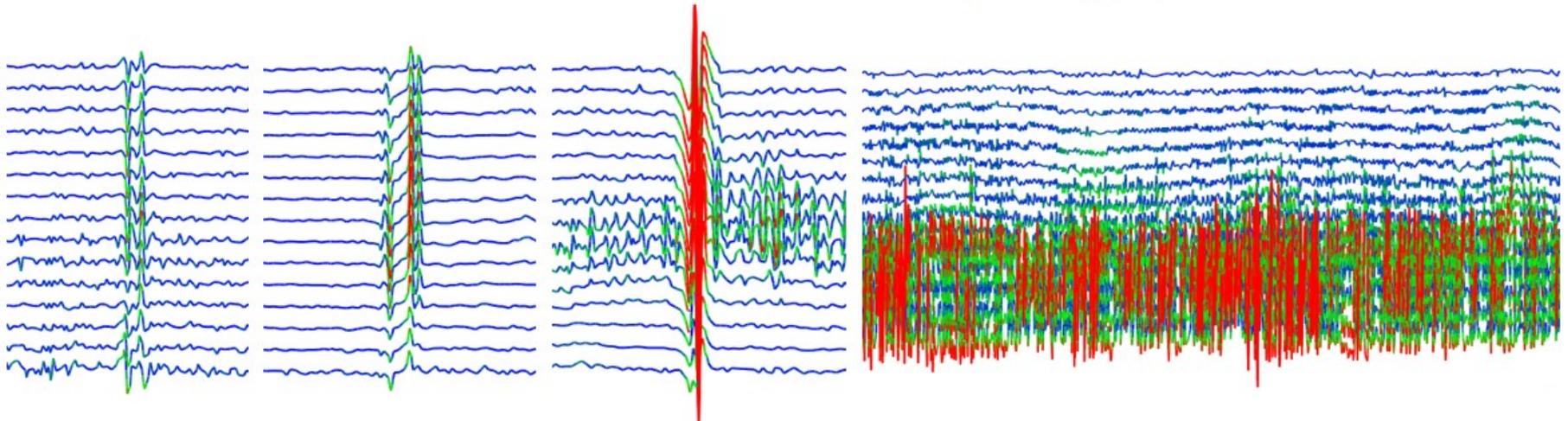


Flashbutt Weld

Aluminothermic Weld

Rail End

Rolling Contact Fatigue (RCF)



## • Surface Map

### Sample Report \*

RTI can customise the reporting to client requirements

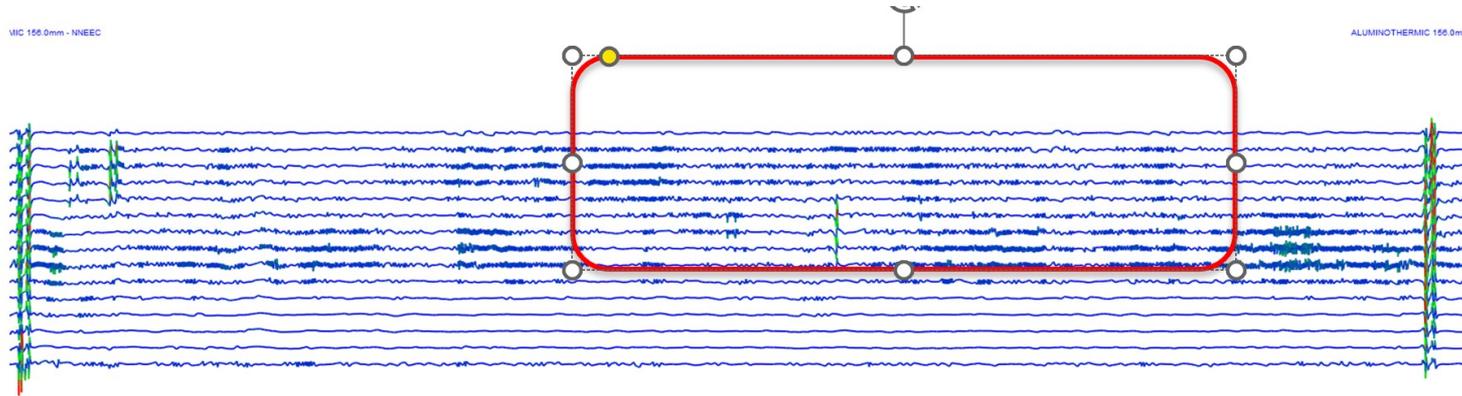
Side	Track	Odometer	Latitude	Longitude	Length (m)	Sub Severity	Width (mm)	Estimated depth (mm)	Type	Field	Centre	Gauge	ERM	GPS Plot (odo, lat, lon)
Right	"MANUK-MANUKML_MAINL"	1.706622	-36.99484801	174.8748292	0.01	6	30	2	"HCC"	4%	93%	3%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.706612	-36.9948 174.8748
Right	"MANUK-MANUKML_MAINL"	1.705409	-36.99485248	174.8748167	0.01	5	30	2	"SQUAT"	5%	92%	3%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.705399	-36.9949 174.8748
Right	"MANUK-MANUKML_MAINL"	1.704819	-36.99485426	174.8748104	0.01	6	25	2	"HCC"	5%	95%	0%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.704809	-36.9949 174.8748
Right	"MANUK-MANUKML_MAINL"	1.704235	-36.99485576	174.8748039	0.01	4	35	3	"SQUAT"	8%	89%	3%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.704225	-36.9949 174.8748
Right	"MANUK-MANUKML_MAINL"	1.703619	-36.99485795	174.8747973	0.01	5	30	2	"SQUAT"	4%	91%	5%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.703609	-36.9949 174.8748
Right	"MANUK-MANUKML_MAINL"	1.702424	-36.99486238	174.8747852	0.011	4	25	3	"SQUAT"	4%	95%	1%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.702413	-36.9949 174.8748
Right	"MANUK-MANUKML_MAINL"	1.698269	-36.9948771	174.8747428	0.011	5	30	2	"SQUAT"	1%	93%	6%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.698258	-36.9949 174.8747
Right	"MANUK-MANUKML_MAINL"	1.697605	-36.99487919	174.8747358	0.061	6	30	2	"HCC"	8%	86%	6%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.697544	-36.9949 174.8747
Right	"MANUK-MANUKML_MAINL"	1.694064	-36.99489204	174.8746997	0.016	5	30	2	"SQUAT"	9%	87%	4%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.694048	-36.9949 174.8747
Right	"MANUK-MANUKML_MAINL"	1.693407	-36.99489438	174.8746929	0.013	6	25	2	"HCC"	5%	91%	4%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.693394	-36.9949 174.8747
Right	"MANUK-MANUKML_MAINL"	1.692216	-36.99489874	174.8746808	0.012	5	30	2	"SQUAT"	1%	91%	8%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.692204	-36.9949 174.8747
Right	"MANUK-MANUKML_MAINL"	1.691071	-36.99490246	174.8746687	0.012	4	30	3	"SQUAT"	5%	89%	6%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.691059	-36.9949 174.8747
Right	"MANUK-MANUKML_MAINL"	1.690044	-36.99490478	174.8746622	0.011	5	25	2	"HCC"	7%	90%	3%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.690429	-36.9949 174.8747
Right	"MANUK-MANUKML_MAINL"	1.689847	-36.99490692	174.874656	0.012	3	30	5	"SQUAT"	6%	89%	5%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.689835	-36.9949 174.8747
Right	"MANUK-MANUKML_MAINL"	1.689238	-36.99490903	174.8746499	0.012	6	25	2	"HCC"	7%	90%	3%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.689226	-36.9949 174.8746
Right	"MANUK-MANUKML_MAINL"	1.688658	-36.99491112	174.8746441	0.013	4	30	3	"SQUAT"	3%	89%	8%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.688645	-36.9949 174.8746
Right	"MANUK-MANUKML_MAINL"	1.687446	-36.99491532	174.8746315	0.011	6	30	2	"HCC"	2%	83%	15%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.687435	-36.9949 174.8746
Right	"MANUK-MANUKML_MAINL"	1.686934	-36.99491745	174.8746262	0.086	4	70	3	"SQUAT"	23%	60%	17%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.686848	-36.9949 174.8746
Right	"MANUK-MANUKML_MAINL"	1.686292	-36.99491977	174.8746198	0.013	4	30	3	"SQUAT"	2%	83%	15%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.686279	-36.9949 174.8746
Right	"MANUK-MANUKML_MAINL"	1.685709	-36.99492137	174.8746131	0.012	5	25	2	"SQUAT"	1%	92%	7%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.685697	-36.9949 174.8746
Right	"MANUK-MANUKML_MAINL"	1.685412	-36.99492224	174.8746101	0.194	6	25	2	"HCC"	3%	97%	0%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.685218	-36.9949 174.8746
Right	"MANUK-MANUKML_MAINL"	1.68516	-36.99492357	174.8746077	0.167	3	30	5	"SQUAT"	3%	93%	4%	"KiwiRail"~"MANUK"~"MANUKML_MAINL"~2025-02-20~02-35-23~1.727000"Dec 1.684993	-36.9949 174.8746

### Customised reporting version

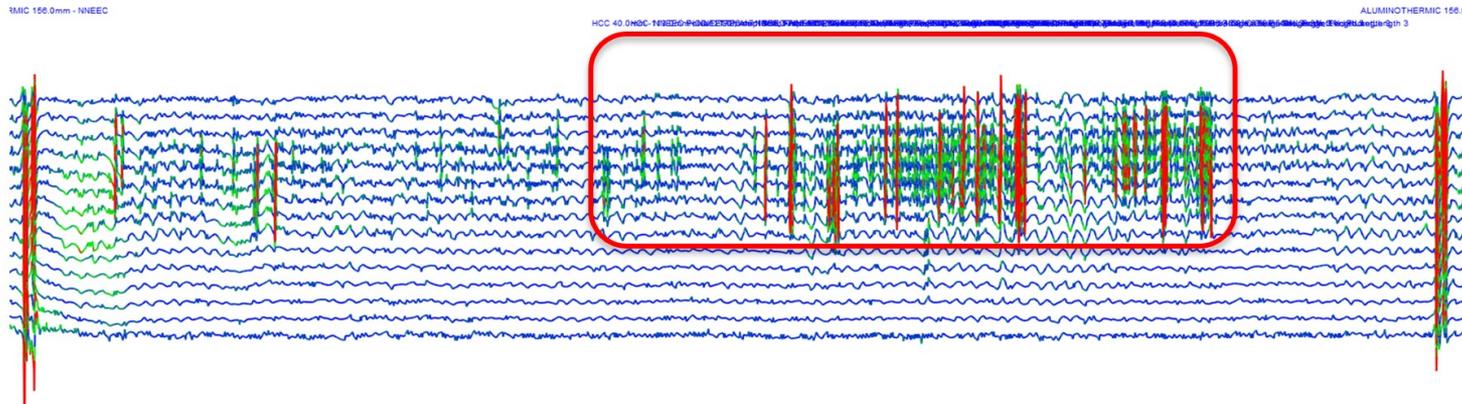
Rail Side	Track	Challage (Km)	"All" Surface Defect at LHRH Rail Conditional Index	"Squat" Surface Defect at LHRH Rail Conditional Index	Rail Side	Track	Challage (Km)	"All" Surface Defect at RHRR Rail Conditional Index	"Squat" Surface Defect at RHRR Rail Conditional Index
LHRH	"EAL-EAL02_DT"	95.320			RHRR	"EAL-EAL02_DT"	95.320	8	8
LHRH	"EAL-EAL02_DT"	95.325			RHRR	"EAL-EAL02_DT"	95.325		
LHRH	"EAL-EAL02_DT"	95.330	12		RHRR	"EAL-EAL02_DT"	95.330	4	
LHRH	"EAL-EAL02_DT"	95.335	6		RHRR	"EAL-EAL02_DT"	95.335	16	
LHRH	"EAL-EAL02_DT"	95.340	6		RHRR	"EAL-EAL02_DT"	95.340	12	
LHRH	"EAL-EAL02_DT"	95.345			RHRR	"EAL-EAL02_DT"	95.345		
LHRH	"EAL-EAL02_DT"	95.350			RHRR	"EAL-EAL02_DT"	95.350		
LHRH	"EAL-EAL02_DT"	95.355			RHRR	"EAL-EAL02_DT"	95.355		
LHRH	"EAL-EAL02_DT"	95.360			RHRR	"EAL-EAL02_DT"	95.360		
LHRH	"EAL-EAL02_DT"	95.365			RHRR	"EAL-EAL02_DT"	95.365		
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LHRH	"EAL-EAL02_DT"	95.375	5		RHRR	"EAL-EAL02_DT"	95.375		
LHRH	"EAL-EAL02_DT"	95.380	2		RHRR	"EAL-EAL02_DT"	95.380	7	
LHRH	"EAL-EAL02_DT"	95.385			RHRR	"EAL-EAL02_DT"	95.385		
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LHRH	"EAL-EAL02_DT"	95.520			RHRR	"EAL-EAL02_DT"	95.520		
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LHRH	"EAL-EAL02_DT"	95.530			RHRR	"EAL-EAL02_DT"	95.530		
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LHRH	"EAL-EAL02_DT"	95.650			RHRR	"EAL-EAL02_DT"	95.650		
LHRH	"EAL-EAL02_DT"	95.655			RHRR	"EAL-EAL02_DT"	95.655		
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LHRH	"EAL-EAL02_DT"	95.725			RHRR	"EAL-EAL02_DT"	95.725		
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● Surface Map

Trending and Repeatability



Testing on 20<sup>th</sup> September 2024

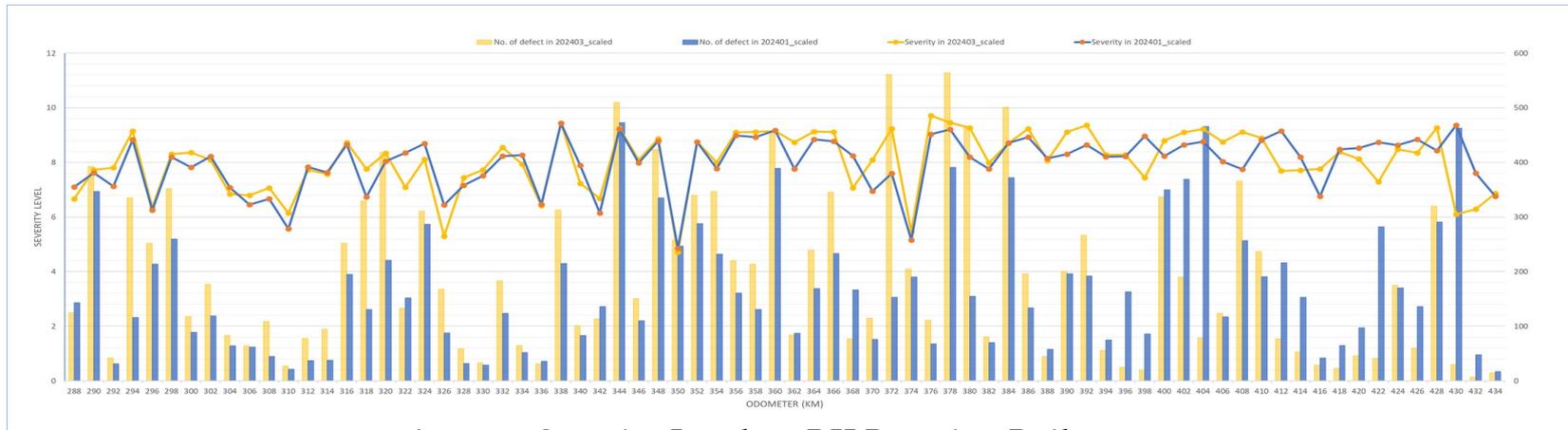


Testing on 01<sup>st</sup> March 2025 (RCF was found at Head Centre & Field Side)

• Surface Map

Trending over Multiple Runs

Average Severity Level on LH Running Rail



Average Severity Level on RH Running Rail





Dual-use intelligent comprehensive inspection vehicle



# Dual-use intelligent comprehensive inspection vehicle

## • Vehicle Introduction

Highway and railway dual-use intelligent comprehensive inspection vehicle is equipped with 3D laser scanner, line scan camera, intelligent track inspection or track geometry status detection system, which can be widely used for comprehensive inspection of highway tunnels, mainline railway routine, and urban rail transit. At the same time, it can be used for emergency rescue of various transportation lines, as an accident site monitoring and remote monitoring platform.



## • Major Function

- **Pure electric drive:** The vehicle is powered by pure lithium batteries, zero release, and suitable for the emission requirements of tunnel operation;
- **All terrain off-road:** The vehicle adopts four-wheel independent suspension and four-wheel drive, and has all-terrain off-road capability with strong overload capability.
- **Remote control:** When the vehicle is traveling on the track, It has two modes of manual driving and remote control driving;
- **Remote monitoring:** The vehicle is equipped with environmental video, real-time data transmission system, and satellite positioning system, which can remotely monitor the vehicle's operating status, location information and running trajectory in real time;
- **Harmful gas detection:** The vehicle is equipped with harmful gas detection system, 2 types of harmful gases can be customized according to user requirement (up to 8 types);
- **Laser scanning and line camera scanning:** It can detect tunnel structural deformation and apparent defects, and generate tunnel surface laser images using point clouds.
- The vehicle can be equipped with one of the following three devices: intelligent track inspection system, track geometry state detection system and Ground Penetrating Radar Detection system.



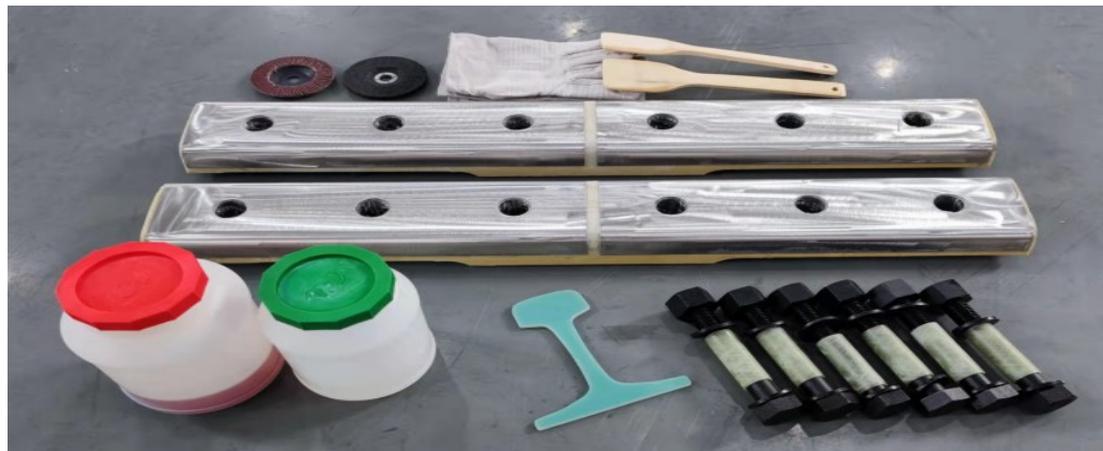
**Adhesive Insulation Joint**

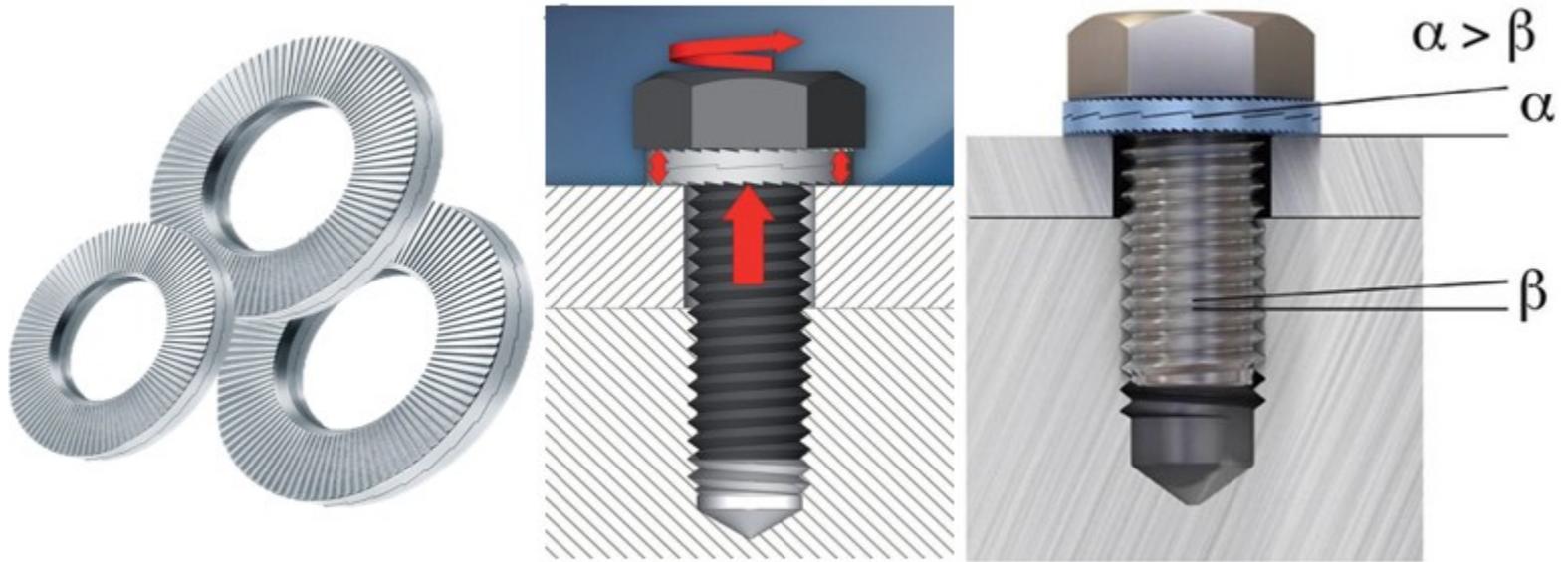


# Adhesive Insulation Joint

## • Product Introduction

The on-site bonding insulation joint of steel rails is suitable for the automatic block track circuit separation section of continuous welded rail (CWR) lines, and is one of the key technologies for laying rail section on CWR lines. The product complies with the railway technical standard "Rail Bonding Insulation Joint" (TB/T2975-2018) and relevant regulations of CRCC (China Railways Test and Certification Center) product certification. The STK-XJ on-site adhesive insulation joint comes in two specifications, STK-XJ50 and STK-XJ60, and is suitable for the construction, installation, and daily maintenance of new high-speed and conventional lines with a rail capacity of 50 kg/m and 60 kg/m. The product meets high standards and has wide applicability. This product has been independently developed and produced since 2003, promoted for use on Chinese railway lines in 2008, and passed CRCC product certification in 2013. Up to now, this product has been continuously used in Chinese railways for nearly 20 years, with a total sales of nearly 90,000 units. This product has been successfully applied on various railway lines in China and has withstood various environmental tests such as extreme cold, humid heat, sandstorms, and frozen soil.





Anti-Loose Washer

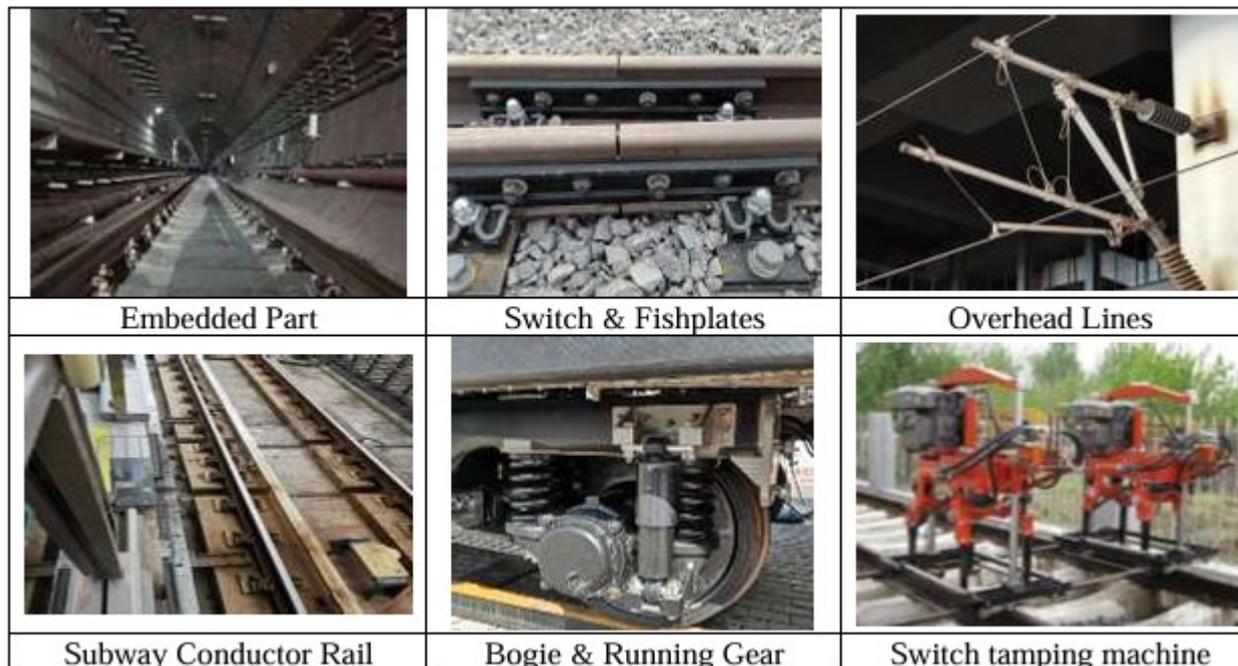


# Anti-Loose Washer

## • Product Introduction

ANTI-LOOSE washer is composed of two parts. When the bolt is pre-tightened, the large tooth surface between the two parts is wedged to engage, thereby achieving the self-locking function.

ANTI-LOOSE Washer is designed with the big tooth bevel angle " $\alpha$ " greater than the thread lead angle " $\beta$ ". In this way, the two washers become staggered when the bot loosens due to the greater distance in lift distance than the thread lift distance of washer. This expansion behavior in the axial direction in return leads to an increase in clamping force, enabling an effective lock the device under conditions of vibration, stress changes, temperature fluctuations, and other states



钢轨探伤检测服务



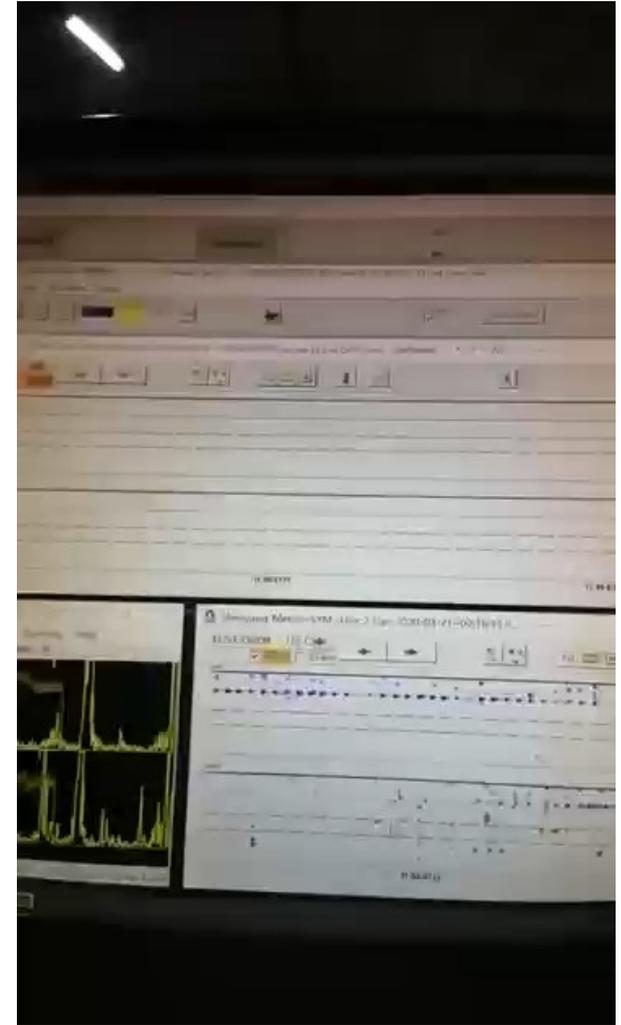
Related Detection Services



# Related Detection Services



# Related Detection Services



# Related Detection Services



# “Enhancing traffic safety”



Feel free to ask questions or exchange ideas